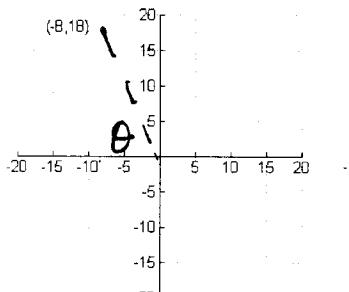


Polar Coordinates and Rectangular Coordinates

Name _____

Change to Polar Coordinates

1. $(-8, 18)$

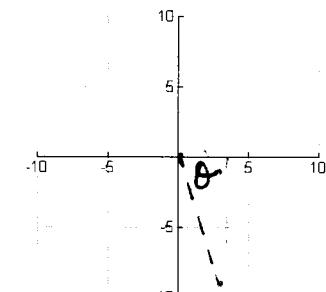


$$\tan^{-1}\left(\frac{18}{8}\right) = 66.04^\circ$$

$$\sqrt{8^2 + 18^2} = \sqrt{388}$$

$$[\sqrt{388}, 113.96^\circ]$$

2. $(3, -9)$

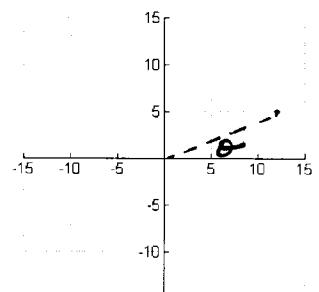


$$\tan^{-1}\left(\frac{-9}{3}\right) = 71.57^\circ$$

$$\sqrt{3^2 + 9^2} = \sqrt{90}$$

$$[\sqrt{90}, -71.57^\circ]$$

3. $(12, 5)$

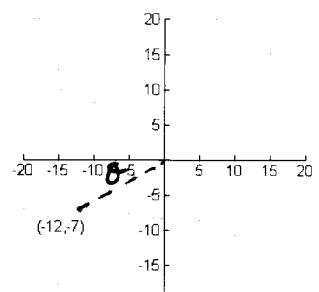


$$\tan^{-1}\left(\frac{5}{12}\right) = 22.62^\circ$$

$$\sqrt{12^2 + 5^2} = 13$$

$$[13, 22.62^\circ]$$

4. $(-12, -7)$



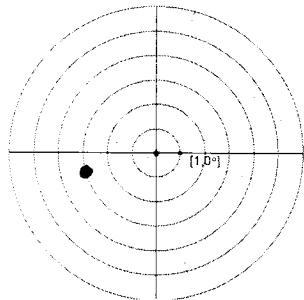
$$\tan^{-1}\left(\frac{7}{12}\right) = 30.26^\circ$$

$$\sqrt{12^2 + 7^2} = \sqrt{193}$$

$$[\sqrt{193}, 210.26^\circ]$$

Graph each polar coordinate and then change it to rectangular coordinates

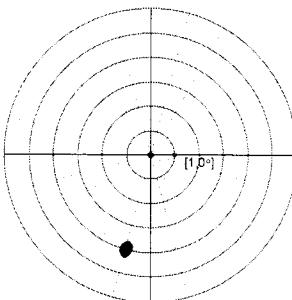
5. $[-3, 15^\circ]$



$$(-3\cos 15^\circ, -3\sin 15^\circ)$$

$$(-2.90, -0.78)$$

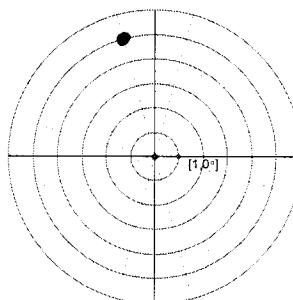
6. $[4, -105^\circ]$



$$(4\cos -105^\circ, 4\sin -105^\circ)$$

$$(-1.04, -3.86)$$

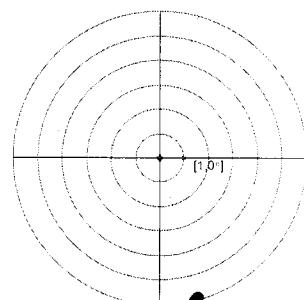
7. $[-5, -75^\circ]$



$$(-5\cos -75^\circ, -5\sin -75^\circ)$$

$$(-1.29, +4.83)$$

8. $[6, 285^\circ]$

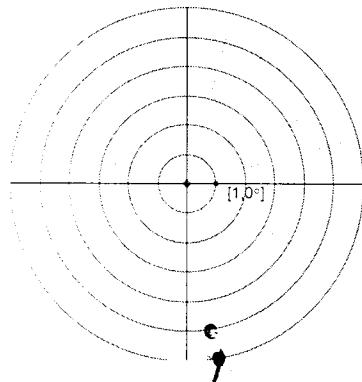


$$(6\cos 285^\circ, 6\sin 285^\circ)$$

$$(1.55, -5.80)$$

Graph these polar coordinates and give three more polar names such that $-360^\circ \leq \theta \leq 360^\circ$

9. $[5, -80^\circ]$

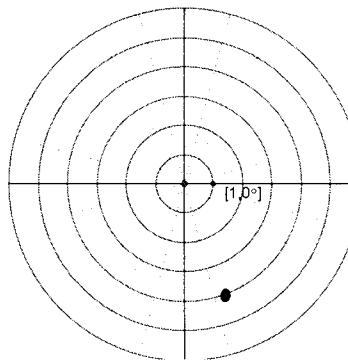


$$[5, 280^\circ]$$

$$[-5, 100^\circ]$$

$$[-5, -260^\circ]$$

10. $[-4, 110^\circ]$

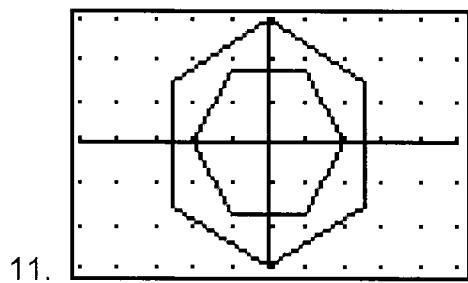


$$[-4, -250^\circ]$$

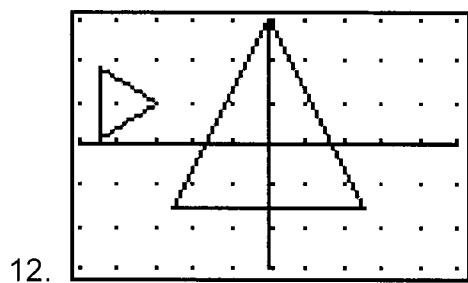
$$[4, -70^\circ]$$

$$[4, 290^\circ]$$

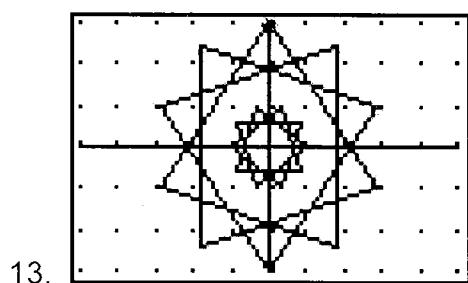
In parametric mode, give the settings needed to produce the following.



$$\begin{aligned}
 X_{1T} &= 2\cos(\tau) & T_{\min} &= 0 \\
 Y_{1T} &= 2\sin(\tau) & T_{\max} &= 360 \\
 X_{2T} &= 3\cos(\tau) & T_{\text{step}} &= 60 \\
 Y_{2T} &= 3\sin(\tau) & \text{where } & 90 \leq t \leq 450 \\
 & & & \text{t step = 60}
 \end{aligned}$$



$$\begin{aligned}
 X_{1T} &= 3\cos(\tau) & T_{\min} &= 90 \\
 Y_{1T} &= 3\sin(\tau) & T_{\max} &= 450 \\
 X_{2T} &= \frac{\cos(t+4)}{\sin(t+1)} & T_{\text{step}} &= 120 \\
 Y_{2T} &= & & 0 \leq t \leq 360 \\
 & & & \text{t step = 120}
 \end{aligned}$$



$$\begin{aligned}
 X_{1T} &= 3\cos(\tau) & T_{\min} &= 90 \\
 Y_{1T} &= 3\sin(\tau) & T_{\max} &= 1170 \\
 X_{2T} &= \cos(\tau) & T_{\text{step}} &= 108 \\
 Y_{2T} &= \sin(\tau) & & 0 \leq t \leq 360 \cdot 3 \\
 & & & \text{t step = 108}
 \end{aligned}$$

14. Rotate triangle ABC around the origin at 160 degrees where A(4, -6) B(-9, 2) C(5, 9)

$$\begin{bmatrix} \cos 160^\circ & -\sin 160^\circ \\ \sin 160^\circ & \cos 160^\circ \end{bmatrix} \begin{bmatrix} A & B & C \\ 4 & -9 & 5 \\ -6 & 2 & 9 \end{bmatrix} = \begin{bmatrix} A' & B' & C' \\ -1.71 & 7.77 & -7.78 \\ -7.01 & -4.96 & -6.75 \end{bmatrix}$$

15. How could you use a matrix to rotate a figure 160 degrees which is NOT centered at the origin?

Translate figure to origin, Rotate using matrices,
 Translate new figure using the opposite
 translation.